

# SOSP: U: EnergyTimers – Integrating Physical Energy Measurement Devices into Operating System Kernels

Luis Gerhorst

Friedrich-Alexander University Erlangen-Nürnberg (FAU)

luis.gerhorst@fau.de

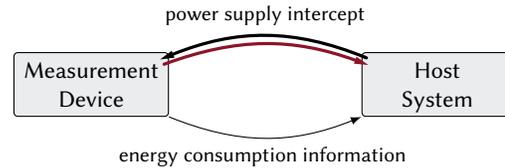
## Abstract

High energy consumption is a problem both in mobile computing systems due to their limited battery capacity, as well as server systems with a constrained cooling capacity. Application developers can improve the energy efficiency of their software if they are able to monitor and profile the energy consumption to discover energy bugs. To support this, I have integrated an external energy measurement device into the standard `perf_event` subsystem of the Linux kernel, which allows the analysis of the energy consumption of applications running on the system under test (SUT). To enable low-overhead self-monitoring, my implementation employs energy timers: the measurement device only notifies the host system when an energy budget has been consumed. My evaluation shows that energy timers can be used to accurately measure the energy consumed by a workload and allow for a overhead-reduction on the SUT by 20 % to 51 % in comparison to regular timers, all while guaranteeing the same level of precision.

## 1 Problem and Motivation

In modern operating systems (OSs) there exist a variety of components dedicated to measuring and quantifying time. Processors offer counters that can be read to identify the current point in time, and also programmable chips (i.e., timers) that notify the processor, usually using an interrupt, when a specified amount of time has elapsed. For energy, however, which is a critical system resource for both small battery-powered devices [16, 27] as well as large scale clusters with thermal constraints [24], only a very limited set of built-in facilities exist to manage it. This is true, especially on the software side [11]. The Portable Operating System Interface (POSIX) defines a variety of interfaces that are related to time, but so far no interface is related to energy [12]. This is due to the fact that only few platforms offer a way to monitor the energy consumed by the system.

On recent Intel processors, the Running Average Power Limit (RAPL) interface allows monitoring of the system’s energy consumption with the help of hardware counters [6]. Using tools such as the Linux kernel’s `perf` [26], this allows userspace to determine how much energy an application consumes. The RAPL interface, however, is only available on recent x86 processors [17]. On embedded platforms and older Intel CPUs, energy measurements are usually not integrated into the hardware at all. And even on Intel processors



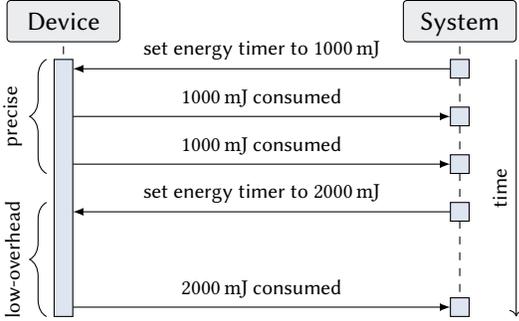
**Figure 1.** The measurement device monitors the power consumption of the host system by intercepting its power supply. The energy consumed is transmitted using discrete packets while the current power draw is monitored continuously.

that support RAPL, external devices are regularly required to monitor the system’s *physical* energy consumption, because only recently, RAPL has switched from model-based energy estimations to actual physical measurements [7]. To summarize, for accurate physical energy analysis custom hardware and software is the dominant measurement setup [4, 5, 9, 13, 18, 23]. This however, leads to results that are hard to reproduce and vulnerable to bugs, ultimately leading to measurement errors. As an universally available RAPL is likely to not exist soon, external energy measurement devices have to be integrated into operating system kernels to allow for reproducible, accurate and low-overhead physical energy measurement.

In this paper, I propose the simple but powerful EnergyTimer protocol, which enables OSs to implement a variety of services employing external energy measurement devices. I have integrated my protocol into the Linux kernel’s `perf_event` subsystem. My work allows measuring an application’s physical energy consumption with an external device, using the standard `perf` utility as interface.

## 2 Approach and Uniqueness

A generic measurement setup for a system that monitors its own energy consumption using an external device is shown in Figure 1. The device determines the power consumption by intercepting the power supply of the host system. The digitized power values are then integrated, producing the amount of energy consumed by the system. In naive custom hardware and software setups, the digital channel from the measurement device to the host system may, for example, continuously stream power samples to the host system. This however, leads to continuous overhead on the host system as it either has to integrate over power samples in real-time,



**Figure 2.** Example showing the packets sent between the measurement device and the host system with EnergyTimers. Blue bars indicate EnergyTimer induced activity.

or store all power values, which can in turn induce noticeable overhead due to disk accesses. To avoid this problem, a dedicated system can be used to store the samples without generating overhead on the system under test (SUT) [9]. However, this requires complicated synchronization of the two systems to correlate software events with power profiles [18]. I propose that instead the following protocol is used:

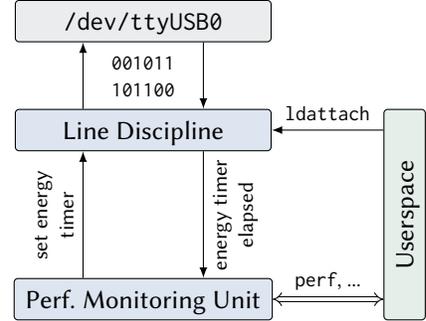
- The host system instructs the measurement device to notify it whenever a certain energy budget has been consumed. It sets an *energy timer*.
- The measurement device continuously integrates over the power values and only notifies the host system when the previously defined energy budget has been consumed [5, 13].

The communication between the host system and the measurement device is illustrated by example in Figure 2. The protocol allows for a simple trade-off between precision, where the set energy timer is small, leading to a frequent interrupt, and accuracy, where the interrupt is infrequent, causing less overhead. This allows it to be applied in a variety of domains each with different classes of workloads. Besides being broadly applicable, energy timers also greatly simplify the budgeting of energy usage with regard to regular timers, where the user has to frequently poll whether the budget has been consumed already.

### 3 Results and Contribution

To demonstrate the soundness and practicality of my approach, I have implemented it on the SAMA5D3 Xplained [25] embedded Linux system<sup>1</sup> in which the measured energy consumption is made available to userspace using the perf tool. The design and usage of the measurement system is described in Section 3.1. Thereafter, Section 3.2 evaluates the

<sup>1</sup>The source code is available at <https://gitlab.cs.fau.de/i4/pub/energytimers> under an open-source license.

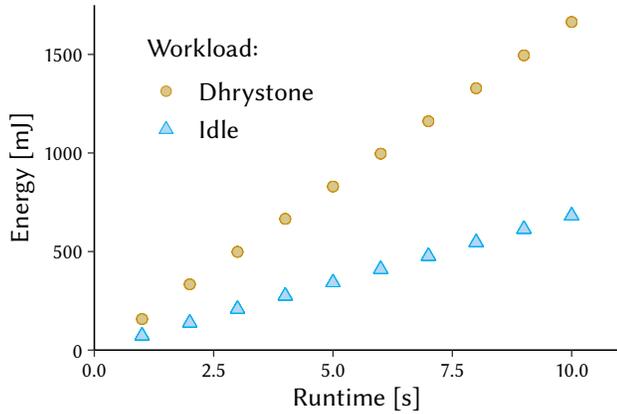


**Figure 3.** Illustration displaying the interacting subsystems when EnergyTimers are used for energy measurements. Initially, userspace attaches the custom line discipline to a serial port on which an EnergyTimers compliant measurement device is connected. Thereafter, the line discipline interprets the timer packets and feeds them into the EnergyTimers performance monitoring unit from which userspace can request the information, for example using the standard perf utility.

overhead and accuracy of the physical energy measurements performed using my tool.

#### 3.1 Implementation

My implementation of the EnergyTimers protocol includes both a kernel module that communicates with the external measurement device, as well as a simple firmware for an AVR microcontroller which constitutes the measurement device. For current and voltage measurements, the microcontroller employs the LTC2991 current and voltage analog-to-digital converter (ADC) [8]. In my prototype, the microcontroller and the host system communicate using a serial line. This has the advantage that the overhead is kept to a minimum in comparison to, for example, a network connection, while the interface is still available on a variety of devices. The communication protocol executed over the serial line employs tested and well-documented methods whenever possible, for example, the Serial Line Internet Protocol (SLIP) is used for framing [19], and XMODEM’s CRC-16 is used to ensure data integrity [3, 10]. To minimize the amount of data, and therefore overhead, data is encoded in binary form. Figure 3 displays an overview over the interacting subsystems when my kernel module is used for energy measurements. The module registers both a line discipline as well as a perf performance monitoring unit (PMU). When a new measurement device is connected to a serial port on the host system, the user simply attaches the custom line discipline to that serial port, using for example, `ldattach` [20]. This causes data received on this port to be interpreted as EnergyTimer packets which constitute the notifications from the measurement device about consumed energy budgets. In response to these, the perf counter is updated. Note that the bytes received on this particular serial line are not copied to userspace. The



**Figure 4.** Energy consumption of the SAMA5D3 Xplained processor core while idle and under load measured using the EnergyTimers perf PMU. As expected the amount of energy consumed increases linearly with the runtime because of the constant power draw. The mean power draw during Dhrystone is  $2.4 \times$  higher than the power draw during idle.

module exports sysfs files that allow userspace to control how often the system is notified by the measurement device. Notifications can either be energy or time-driven, that is, the system is either notified whenever a set timer elapses or whenever a certain amount of micro joules has been consumed. To ensure portability, the code implementing the protocol is encapsulated in a library which at this point is already used by both the kernel module and the AVR firmware. Using my work, an application developer can measure the energy consumed by their application simply by entering the command shown in Listing 1.

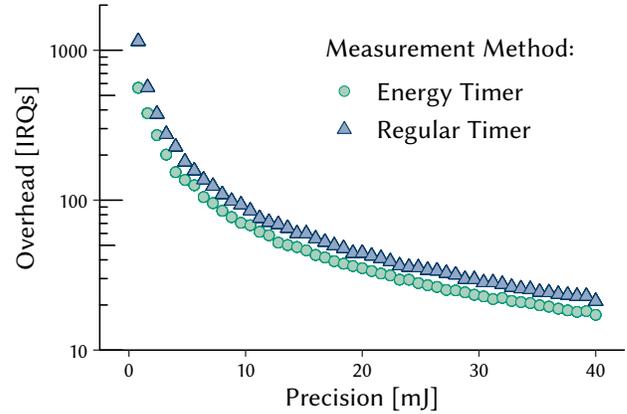
**Listing 1.** Using `perf stat`, application developers can easily determine the amount of energy a task consumed using the EnergyTimers (et) PMU.

```
perf stat -e et/energy/ my_app
# -> e.g., 1.664 joule
```

### 3.2 Evaluation

To confirm the correctness of my implementation, I have measured the power consumption of known workloads on the SAMA5D3 Xplained board. Figure 4 shows the energy consumed by the processor, the embedded memories and the peripherals<sup>2</sup> while idle and during the Dhrystone benchmark, measured using an energy timer of 8.0 mJ. Each measurement presented in this section represents the mean value calculated from 10 samples. The variation was always below the displayed resolution (i.e., point size for graphs and

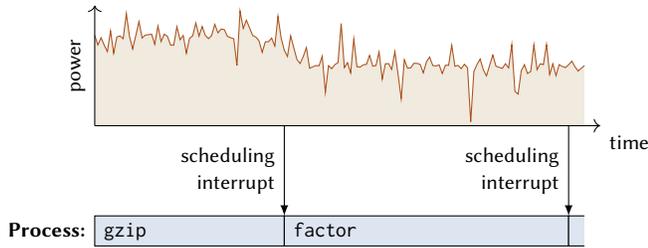
<sup>2</sup>Measured by intercepting VDDCORE using JP1. As described in the board’s user guide [1], the incorrect JP1 routing was fixed.



**Figure 5.** Measurement displaying the tradeoff between overhead and precision enabled by EnergyTimers. To guarantee the same level of precision, energy timers require fewer packets to the host because regular timers force the user to assume the worst-case power draw, that is the maximum power draw possible, occurred since the last notification.

number of digits for numbers). While idle, my tool reports a mean energy consumption of 68.2 mW. During the Dhrystone benchmark a mean power consumption of 166.4 mW is reported. This closely matches the power consumption during Dhrystone reported by Atmel in the board’s datasheet, which is 162.5 mW [2].

To guarantee the same level of precision when keeping track of the energy consumed, energy timers require less overhead on the host system than regular timers. Energy timers guarantee to the processor, that since the last notification, at most the set energy budget has been consumed. When a regular timer is used instead, the processor can not know whether the pending interval is one with large or small energy consumption. Therefore, to guarantee that at most a certain amount of energy was consumed in the meantime, the user has to assume that the maximum power draw possible occurred since the last notification. This causes the timer interval derived to be unnecessary small as the device rarely consumes that much power during a typical workload. The small interval causes more frequent interruptions to the SUT and therefore hurts measurement trueness. To demonstrate this advantage of energy timers, I have measured the energy consumption of a fixed workload using both energy timers between 0.8 mJ and 40.0 mJ, as well as regular timers between 4 ms and 200 ms. Unfortunately, Microchip does not list any information on the maximum power draw of the core components in the datasheet or user guide of the SAMA5D3 Xplained board [1, 2, 25]. Still, this information is required to determine the guaranteed level of precision for energy measurements when regular timers are used. Therefore, the user has to estimate the value based on additional measurements.



**Figure 6.** Illustration displaying how EnergyTimers can be used for energy-driven scheduling. Applications with increased power draw due to IO (`gzip`) get preempted earlier than applications that only exercise the processor (`factor`).

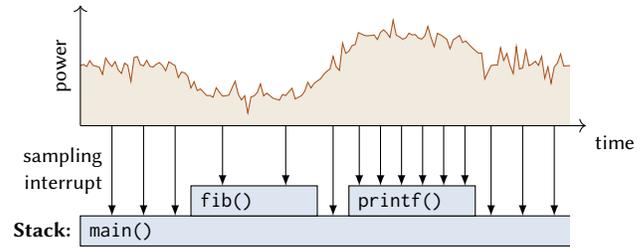
Energy timers in turn, do not require this information in the first place which is another advantage. My measurements show a maximum power consumption for the board of *at least* 178.0 mW. Given some headroom I therefore estimate 200.0 mW to be the upper limit. Assuming this maximum power draw, Figure 5 displays how energy timers compare to regular timers regarding the overhead required for a given guaranteed level of measurement precision. Overhead constitutes itself in the number of notifications to the host system that update the energy counter maintained by `perf`. The guaranteed precision of the measurement is simply the set energy budget, or if regular timers are used, the timer interval multiplied with the previously estimated maximum power draw. Because of the overestimation that is required for regular timers, energy timers allow for lower overhead than regular timers while guaranteeing the same level of precision.

## 4 Future Work

In future work EnergyTimers may be used to implement a variety of other OS services besides simple energy measurements. Using EnergyTimers, a scheduler can, for example, preempt applications based on energy budgets not CPU time budgets as illustrated in Figure 6. Also, interrupts occurring every  $N$  joules can be used to determine *where* in an application most of the energy is consumed [5, 21]. Figure 7 illustrates how increased energy consumption in a subroutine causes a greater number of profiling samples be collected for the code section when the energy timer is sufficiently small. For this, the interrupt handler must record the current context, for example, the current value of the instruction pointer, for later analysis which may be implemented using `perf`'s sampling capabilities.

## 5 Related Work

Le Sueur and Heiser demonstrated that generic processor features like dynamic voltage and frequency scaling (DVFS) as well as C states (sleep modes) can save power [15], but also that the power savings drawn from DVFS are limited [14].



**Figure 7.** EnergyTimers allow for energy-driven statistical sampling. The more energy a subroutine consumes, the higher is the number of samples for that routine, therefore indicating where an application consumes the most energy.

This pushes more of the responsibility to make systems energy efficient towards application developers, who have to profile their applications to identify bottlenecks. This however, is only possible if the OS provides them with the appropriate tooling for this task.

Flinn and Satyanarayanan developed PowerScope, a tool which allows consumed energy to be attributed to individual processes and procedures [9] using time-based statistical sampling of the power consumption. EnergyTimers in comparison, allow for energy-based statistical sampling.

Weissel and Bellosa [28] use performance counters to estimate the optimal clock frequency for an application, trading in minor performance losses for substantial power savings. Although RAPL was not available in 2002, they already acknowledge that performance counters designed for energy profiling would benefit their approach. In 2020, these are still not ubiquitous, suggesting that external energy measurement devices will continue to be used in the future.

To date, various energy monitoring devices have been presented in the literature [22, 23]. Jiang et al. designed sensor nodes that use a separate energy counter to monitor their own energy consumption [13]. Their measurement device therefore is similar to an EnergyTimers compliant measurement device, however, I am focusing on integrating such a device into modern operating system kernels. All of the referenced monitoring devices use microcontrollers in between the ADC and the system that stores the measurements. This shows that the hardware required for EnergyTimers is already widespread and a potential user only has to flash the adapted EnergyTimers firmware<sup>3</sup> onto their microcontroller.

Zeng et al. have proposed the *Currentcy* model which allows an OS to manage energy as a first-class resource [29, 30]. For their implementation however, the absence of a generic interface for energy consumption forces them to rely on approximations which are sufficiently accurate but very system specific. A generic interface would allow their approach to be applied in a broad variety of systems.

<sup>3</sup>The source code is available for the LTC2991 voltage and current monitor on <https://gitlab.cs.fau.de/i4/pub/energytimers/firmware-ltc2991>.

## 6 Conclusion

This paper presented energy timers, which are a powerful concept that allows for the integration of external energy measurement devices into OS kernels. I have integrated energy timers into the Linux `perf_event` subsystem, giving users a convenient and powerful interface to perform physical energy measurements. My evaluation shows that energy timers both allow for accurate measurements, but also that they outperform traditional timers regarding their guaranteed precision. In future work, energy timers may be used for energy profiling and also energy-driven scheduling.

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